

## Digital Scanning Direction Finders DDF0xS

Fast and reliable interception of complex signals

- High scanning speed: $200 \mathrm{MHz} / \mathrm{s}$ for 8 kHz resolution ( 6 dB bandwidth) and 200 kHz FFT realtime bandwidth
- High selectivity
- Convenient user interface
- Excellent system compatibility through
- effective data compression
- integrated controller for hand-off receivers
- system integration via all common data interfaces
- Wide range of antennas for stationary and mobile use from 0.5 to 1300 MHz
- Algorithms for correlative interferometer and Watson-Watt method as standard
- Use in automatic radiolocation systems with high probability of intercept
- Direction finding of frequencyhopping, burst and broadband signals
- Data reduction can be optimized according to frequency-, time- and directionselective criteria
- For HF direction finding using the correlation method, the elevation can also be determined, which allows single-station location (SSL) systems to be implemented
- Versatile stationary and mobile applications (vehicle, ship, aircraft) through the use of different DF algorithms and antenna configurations, especially wide-aperture arrays


## System overview

The DDF0xS family of scanning direction finders covers the frequency range 0.5 MHz to (650) 1300 MHz . The type designations are:

HF:
DDF01S 0.5 MHz to 30 MHz HF/VHF/UHF:
DDF06S 0.5 MHz to (650) 1300 MHz
Each direction finder comprises three functional groups: a DF antenna system, a DF converter including three DF receiver modules, and a digital signal processing unit.

The HF direction finder consists of HF DF Converter EH091 and Digital Processing Unit EBD92D. The same equipment is used for the VHF/UHF range, butwith VHF/UHFDF Converter ESMA33 connected ahead of the direction finder. ESMA33 converts the received signals to the IF ( 21.4 MHz )

and routes them to HF DF Converter EH091.

The DF system is operated via an external computer that also displays the results.

The software of the digital processing unit contains as a standard the
algorithms for DF evaluation according to the correlative interferometer or the Watson-Watt method, so that either of the methods can be used depending on available antenna system and operational requirements.


## Digital DF methods

Scenarios with rapidly changing situations, for example as a result of frequency-hopping transmitters or burst transmissions, become more and more frequent and require new concepts for reconnaissance systems.

If signal detection and direction finding/locating are performed using separate units, it is not uncommon that a newly discovered frequency activity cannot be passed on to the DF system because of its short duration and so the signal remains undetected. State-of-theart systems should therefore be capable of determining frequency, level and bearing of such signals simultaneously.

Concepts of this kind have so far been implemented by analog systems. The scanning speed of such systems is however limited due to the time required for synthesizer switching and filter settling.

The DDF $0 \times S$ generation of direction finders makes use of fast Fourier transform (FFT), which allows several signals to be analyzed simultaneously within a wide frequency band and a selectable resolution bandwidth.

The complex antenna voltages are measured by a high-grade triple DF receiver that acts like a vector voltmeter. The measured values are digitized. The results are evaluated on the basis of mathematical algorithms simultaneously and separately for each signal. Evaluation can be performed using classic DF methods such as Watson-Watt or interferometer or, preferably, state-of-the-art correlation methods (correlative interferometer).

The correlation principle offers the following advantages over the classic methods:

- Reduction of DF errors caused by reflection and depolarization
- Use of wide-aperture DF antennas with a minimum number of antenna elements (also arranged in circular arrays)
- The elements forming the DF antenna system can basically be arranged in any configuration
- In mobile use highly effective reduction of bearing errors caused by platform (vehicle, ship, aircraft) through correction

The essential features of the
Watson-Watt method are:

- Maximum scanning/DF speed since only one measurement step is required per FFT window
- Adcock antennas, especially those for the HF range, can easily be adapted
direction finders can be equipped with a GPS receiver (option EBD92GP) that delivers a highly precise sync pulse as well as the time stamp ( $1 \mu \mathrm{~s}$ resolution) necessary for position finding.


## Operation and displays

All operating and display functions are performed via a PC by means of the software supplied as standard. Signal activities and bearings are displayed on the screen which is divided into several windows. The user can select and arrange the windows according to his operational requirements. The following display modes are available:

Amplitude versus frequency (spectrum display), bearing versus frequency, bearing or level versus frequency and time (waterfall), elevation versus frequency. Most parameters can also be displayed in the form of histograms. Colour scales can be activated in the windows to visualize the magnitude of bearing and level. The DF values measured at the individual frequencies can be displayed numerically at a keystroke. The associated frequency and level values are also shown as numerals. The user can select whether instantaneous values or results obtained by histogram averaging are displayed. Actions are triggered by clicking icons on the user interface or pressing hardkeys. Only those control

User interface with typical scenario of broadband emitters in HF band. Waterfall display (top) reveals frequency-agile emitters; histogram (bottom right) allows unambiguous identification of weak frequency-hopped signals from overlapping frequency bands of same azimuth sector.
elements that are constantly needed are permanently displayed.

The direction finder basically operates in two modes: the scan mode and the fixed-frequency mode (FFM).

## Scan mode

In the scan mode, which is probably the most important operating mode, the FFT window with a width of 200 kHz is shifted stepwise at high speed within one or several scan ranges. Each scan range is defined by the start and stop frequency as well as by the resolution of the scan. If an activity is detected that is confined to a specific subrange, the user can define and activate a zoom range using the mouse. The defined range will then be scanned at high speed, which increases the probability of intercept. As all results of the preceding 60 seconds are permanently stored in the background, the parameters of FH or burst signals encountered unexpectedly can be evaluated later on with the aid of the memory. It is furthermore possible to record data over an extended period of time, although the duration of recording

depends on the space available on the hard disk. For data compression a maximum of two azimuth ranges of interest can be selected when defining the scan range. All results outside these ranges will be suppressed. In addition, the user can enter maximum/minimum values for signal duration and period as well as elevation limits (HF, correlative interferometer).

Fixed-frequency mode (FFM)
The only difference between FFM and scan mode is that the 200 kHz analysis
window is not shifted but stays fixed at a frequency. This center frequency is selected and marked in the scan mode using the frequency cursor. The maximum probability of intercept is guaranteed for this narrow range.

As the direction finders of the DDFOxS family are not provided with an integrated demodulator because they are mainly used in the scan mode, the frequency information may be sent to hand-off receivers for further processing. If the user detects a

Scanning speeds

|  | Scanning range > $\mathbf{2 0 0} \mathbf{~ k H z}$ (SCAN) |  |  |  | Scanning range 200 kHz (FFM) |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Resolution | Time for $\mathbf{2 0 0 ~ k H z ~ ( i n ~ m s ) ~}$ |  | Scanning speed (in MHz/s) |  | Time for 200 kHz (in ms) |  | Scanning speed (in MHz/s) |  |
| HF range | Watson-Watt | Correlation | Watson-Watt | Correlation | Watson-Watt | Correlation | Watson-Watt | Correlation |
| 125 Hz | 69 | 363 | 3 | 0.6 | 66 | 384 | 3 | 0.5 |
| 250 Hz | 37 | 184 | 5 | 1.1 | 34 | 194 | 6 | 1.0 |
| 500 Hz | 21 | 93 | 10 | 2.2 | 17 | 96 | 12 | 2.0 |
| 1 kHz | 13 | 49 | 15 | 4.1 | 9 | 51 | 22 | 3.9 |
| 2 kHz | 9 | 25 | 22 | 8.0 | 5 | 26 | 40 | 7.7 |
| $\mathrm{V} / \mathrm{UHF}$ range |  |  |  |  |  |  |  |  |
| 4 kHz | 1.6 | 5.0 | 125 | 40 | 1.6 | 5.0 | 125 | 40 |
| 8 kHz | 1.0 | 4.0 | 200 | 50 | 1.0 | 4.0 | 200 | 50 |
| 16 kHz | 1.0 | 4.0 | 200 | 50 | 1.0 | 4.0 | 200 | 50 |
| 32 kHz | 1.0 | 4.0 | 200 | 50 | 1.0 | 4.0 | 200 | 50 |

frequency of interest in the scan mode or FFM, he places the cursor on this frequency and activates one of the receiver symbols in the transfer bar. The selected receiver allows the signal in
question to be intercepted, recorded or analyzed. The operating parameters for the receivers (demodulation mode, bandwidth, level threshold) can already be defined when determining
the scan range. To obtain a bearing the direction finder can also be set to the desired frequency by means of an external receiver.

## CertifiedQualitySystem



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## Specifications

HF range (DDF01S and DDF06S)
Frequency range
DF method
DF accuracy
Instrumental
With antenna ADDO 11
Sensitivity
(2 ${ }^{\circ}$ rms bearing fluctuation)

FFT realtime bandwidth
Resolution (corresp. to 6 dB BW )
Filter characteristics
Resolution of A/D converter
Scanning speed
Screen display and analysis Display modes

Monitor resolution
Frequency channel width
Cursor functions
Zoom functions
Recording capacity
Offline analysis
Dynamic range
Nominal impedance
Frequency stability
Image frequency rejection
IF rejection
VHF/UHF range (DDF06S)

| Frequency range | 20 MHz to (650) 1300 MHz |
| :---: | :---: |
| DF method | Watson-Watt, correlative interferometer |
| DF accuracy |  |
| Instrumental | $0.7^{\circ} \mathrm{rms}$ (Watson-Watt) |
| With antenna ADD05 1 | $1^{\circ} \mathrm{rms}$ |
| Sensitivity |  |
| $\left(2^{\circ} \mathrm{rms}\right.$ bearing fluctuation) | depending on antenna system: see diagram on page 6 |
| Polarization | vertical |
| Operating modes | - SCAN with 3 modes for data reduction(azimuth selection, time filter, threshold and frequency suppression function) <br> - FFM (fixed-frequency mode) |
| FFT realtime bandwidth | 200 kHz |
| Resolution (corresp. to 6 dB BW) | 4/8/16/32 kHz |
| Filter characteristics | shape factor approx. 4 |
| Resolution of A/D converter | 16 bits |
| Scanning speed | see table on page 4 |

Screen display and analysis
Display modes


## Ordering information

| Digital Scanning Direction Finders 0.5 to 30 MHz , consisting of: | DDFO×S |  |
| :---: | :---: | :---: |
| EBD92D + EH091 | DDFO1S | 4044.8754.02 |
| 0.5 to 650 MHz , consisting of: |  |  |
| EBD92D + EH091 + ESMA33 | DDF06S | 4044.9009.02 |
| 0.5 to 1300 MHz , consisting of: EBD92D + EH091 + |  |  |
| ESMA 33 with ESMA-T2 | DDF06S | 4044.9009.03 |
| Options |  |  |
| GPS for accurate time stamp: | EBD92GP | 4033.0070 .02 |
| Antenna Correction | EBD92AK | 4033.0086.02 |
| Recommended extras |  |  |
| Antenna Interface | GX060 | 4050.8500 .02 |
| Multicoupler | VE010 | 4050.8000 .02 |

## DF antennas

A variety of DF antennas is available to match different applications. The antennas available include Adcock, circular or crossed-loop arrays. For details of antennas see table on page 7 .

All these antennas feature a coding function that informs the connected DF system about the algorithm (correlation or Watson-Watt) to which the direction finder is to be set. Optionally, the antennas for mobile use can be equipped with an electronic compass by which the bearings are automatically referred to magnetic north.

Adapters are available for installing the mobile DF antennas on vehicles or masts, eg on ships.


In many cases, existing installations of non-R\&S antennas (Adcock) can be used with the direction finders provided that Antenna Interface GX060 10.3 MHz to 650 MHz ) is used as well. Details have to be checked in each individual case.

HF DF Antenna ADD0 11


## Multicoupler VE010

Multicoupler VEO 10 makes it possible to operate simultaneously up to six Direction Finders DDF01S or DDF01M (see data sheet PD 757.1854) from one HF DF Antenna ADD010 or ADD011. With VE010, Direction Finders DDFO1M/DDF01S can be connected to the HF DF antenna in any combination and operated completely independently of each other.

## Antenna cables

HF Antenna Cable ADDO1xZ is required for connecting the HF DF antenna to the DF equipment. The cable is available in various lengths to suit the application.

Antenna Cable ADD05xZ is used for the VHF/UHF range. For cable lengths exceeding 10 m, Power Supply IN06 1 is supplied with the cable.

## Effective lightning protection

The cable inputs and outputs of the DF antennas are overvoltage-protected as standard. In the case of VHF/UHF DF Antennas ADD 150, ADD050 and ADD05 1, a lightning rod is supplied to protect the equipment against direct lightning strokes.

Sensitivity of DF antennas; averaging time 1 s , bearing fluctuation $<2^{\circ} \mathrm{rms}$



Overview of available antennas - specifications


## Fax Reply (Digital Scanning Direction Finders DDF0xS)

$\square \quad$ Please send me an offer
$\square \quad$ I would like a demo
$\square \quad$ Please call me
$\square \quad$ I would like to receive your free-of-charge CD-ROM catalog (Test and Measurement Products)

Others: $\qquad$

Name:
Company/Department: $\qquad$
Position: $\qquad$
Address:
$\qquad$

Country:
$\qquad$

Telephone:
$\qquad$

Fax:
E-mail: $\qquad$

